## Relation Algebra and RelView Applied to Approval Voting

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## Introduction

Voting procedures are used in situations if a group of individuals has to come to a common decision:

- Elections of political parliaments.
- Ballots in committees.
- Definition of winners in sports tournaments.
- Awarding of contracts.
- Granting of funds.
- . .
- What to do during the annual works outing?
- What language is used in the beginners lecture of Computer Science?
- ...


## Common Background: Voting Systems

- There is a finite and non-empty set $N$ of voters (agents, individuals, parties etc.). To simplify things one uses:

$$
N=\{1,2, \ldots, n\}
$$

- There is a finite and non-empty set $A$ of alternatives (proposals, candidates etc.).
- Each voter $i$ possesses an individual preference $I_{i}$ in view of the given alternatives.
- There is a voting rule that specifies
- how to aggregate the voter's individual preferences to a collective preference,
- how then to get the set of winners.

Instances $\left(N, A,\left(I_{i}\right)_{i \in N}\right)$ are called elections.

## Example: Approval Voting

- Here the individual preferences are sets of alternatives

$$
A_{i} \in 2^{A}
$$

and $a \in A_{i}$ is interpreted as "voter $i$ approves alternative $a$ ".

- The collective preference is specified via a dominance relation

$$
D: A \leftrightarrow A
$$

such that for all $a, b \in A$ it holds

$$
D_{a, b} \Longleftrightarrow\left|\left\{i \in N \mid a \in A_{i}\right\}\right| \geq\left|\left\{i \in N \mid b \in A_{i}\right\}\right| .
$$

- There always exist alternatives which dominate all alternatives; these are called the approval winners.

Weak dominance and multiple-winners condition.

## Example: Condorcet Voting

- Here the individual preferences are linear strict-order relations

$$
>_{i}: A \leftrightarrow A
$$

and $a>_{i} b$ is interpreted as "voter $i$ ranks alternative $a$ better than $b$ ".

- The collective preference is specified via a dominance relation

$$
D: A \leftrightarrow A,
$$

such that for all $a, b \in A$ it holds

$$
D_{a, b} \Longleftrightarrow\left|\left\{i \in N \mid a>_{i} b\right\}\right| \geq\left|\left\{i \in N \mid b>_{i} a\right\}\right| .
$$

- There is not always an alternative that dominates all alternatives; if such an alternative exists it is called the Condorcet winner.
- If there is no Condorcet winner, then the winners are specified via socalled choice sets (top cycle, uncovered set, Banks set etc.).


## Example: Borda Voting

- Here the individual preferences are injective functions

$$
f_{i}: A \rightarrow\{0,1, \ldots,|A|-1\}
$$

and the value $f_{i}(a)$ is interpreted as "voter $i$ assigns $f_{i}(a)$ points to alternative $a^{\prime \prime}$.

- The collective preference is specified via a dominance relation

$$
D: A \leftrightarrow A,
$$

such that for all $a, b \in A$ it holds

$$
D_{a, b} \Longleftrightarrow \sum_{i \in N} f_{i}(a) \geq \sum_{i \in N} f_{i}(b)
$$

- There always exist alternatives which dominate all alternatives; these are called the Borda winners.


## Control of Elections

Here it is assumed that the authority conducting the election, called the chair, knows the individual preferences of the voters and is able

- to remove voters from the election (by dirty tricks, like mistimed meetings)
- to remove alternatives from the election (by excuses, like "too expensive" or "legally not allowed").

Using constructive control, the chair tries

- to make a specific alternative $a^{*} \in A$ to a winner by a removal of voters / of alternatives
- and (to hide his mind) to remove as few as possible voters / alternatives to reach this goal.

Using destructive control, with the same actions the chair tries to prevent $a^{*}$ from winning.

Control may be hard or easy. E.g., in case of approval voting we have:

- Constructive control via the removal of voters is NP-hard.
- There are efficient algorithms for the constructive control via the removal of alternatives.
In case of plurality voting (another well-known voting system) the complexities change, i.e.:
- Constructive control via the removal of alternatives is NP- hard.
- There are efficient algorithms for the constructive control via the removal of voters.

Our goal: Use of relation algebra and the BDD-based tool ReLView

- for computing dominance relations and winners,
- for the solution of non-trivial instances of hard control problems.

Here: Approval voting and constructive control by a removal of voters.

## Specific Relational Constructions

- The symmetric quotient of $R: X \leftrightarrow Y$ and $S: X \leftrightarrow Z$ is defined as $\operatorname{syq}(R, S)=\overline{R^{\top} ; \bar{S}} \cap \bar{R}^{\top} ; S: Y \leftrightarrow Z$ and from this we get:

$$
\operatorname{syq}(R, S)_{y, z} \Longleftrightarrow \forall x \in X: R_{x, y} \leftrightarrow S_{x, z}
$$

- If the target of a relation is a singleton set, here always $\mathbf{1}=\{\perp\}$, it is called a vector.
We denote vectors by small letters and write $v_{x}$ instead of $v_{x, \perp}$.
A vector $v: X \leftrightarrow \mathbf{1}$ describes the subset $\left\{x \in X \mid v_{x}\right\}$ of its source.
- A point $p: X \leftrightarrow \mathbf{1}$ is a vector which describes a singleton subset $\{x\}$ of $X$.
We then say that it describes the element $x$ of $X$.
- The membership relation $\mathrm{M}: X \leftrightarrow 2^{X}$ is defined as follows:

$$
\mathrm{M}_{x, Y} \Longleftrightarrow x \in Y
$$

- The size-comparison relation $S: 2^{X} \leftrightarrow 2^{X}$ is defined as follows:

$$
S_{Y, Z} \Longleftrightarrow|Y| \leq|Z|
$$

- The projection relations $\pi: X \times Y \leftrightarrow X$ and $\rho: X \times Y \leftrightarrow Y$ are defined as follows:

$$
\pi_{(x, y), z} \Longleftrightarrow x=z \quad \rho_{(x, y), z} \Longleftrightarrow y=z
$$

- The pairing (or fork) of $R: Z \leftrightarrow X$ and $S: Z \leftrightarrow Y$ is defined as the relation $\left[R, S \rrbracket=R ; \pi^{\top} \cap S ; \rho^{\top}: Z \leftrightarrow X \times Y\right.$ and from this we get:

$$
\left[R, S \rrbracket_{z,(x, y)} \Longleftrightarrow R_{z, x} \wedge S_{z, y}\right.
$$

All that is available in the programming language of RELVIEW.

## A Relational Model of Approval Voting

- A relation $P: N \leftrightarrow A$ is called a relational model of $\left(N, A,\left(A_{i}\right)_{i \in N}\right)$ if for all $i \in N$ and $a \in A$

$$
P_{i, a} \Longleftrightarrow a \in A_{i} .
$$

- If $P: N \leftrightarrow A$ is a relational model, then we get

$$
\begin{aligned}
\left\{i \in N \mid P_{i, c}\right\}=Z & \Longleftrightarrow \forall i \in N: P_{i, c} \leftrightarrow i \in Z \\
& \Longleftrightarrow \forall i \in N: P_{i, c} \leftrightarrow \mathrm{M}_{i, Z} \\
& \Longleftrightarrow \operatorname{syq}(P, \mathrm{M})_{c, Z}
\end{aligned}
$$

for all $c \in A$ and $Z \in 2^{N}$ and this shows for the dominance relation

$$
D=\operatorname{syq}(P, \mathrm{M}) ; \mathrm{S}^{\top} ; \operatorname{syq}(P, \mathrm{M})^{\top}: A \leftrightarrow A .
$$

- The set of winners is described by the vector

$$
\operatorname{win}=\overline{\bar{D} ; \mathrm{L}}: A \leftrightarrow \mathbf{1} .
$$

## An Example

- Relational model $P: N \leftrightarrow A$ as RelView-matrix:


$$
\text { Voters } N=\{1,2, \ldots, 12\}
$$

Alternatives $A=\{a, b, \ldots, h\}$

- Dominance relation $D: A \leftrightarrow A$ and vector win : $A \leftrightarrow \mathbf{1}$ as computed by RelView:


How many voters need to be removed such that, e.g., alternative e wins?

The answer to the last question for all alternatives $a, b, \ldots, h$ as computed and shown in a column-wise fashion by RelView (in the same order):


- Positions 2, 6, 7 and 8: No voter needs to be removed to ensure win for $b, f, g$ and $h$.
- Position 4 and 5: Voter 10 needs to be removed to ensure win for $d$ and $e$.
- Position 1: Two voters need to be removed to ensure win for $a$, viz. 2,11 or 5,11 or 6,11 .
- Position 3: Four voters need to be removed to ensure win for $c$ and there are 12 possibilities for this.


## Relational Control of Approval Voting

We assume that $P: N \leftrightarrow A$ is a model of $\left(N, A,\left(A_{i}\right)_{i \in N}\right)$ and $a^{*} \in A$ shall win, where the point $p: N \leftrightarrow \mathbf{1}$ describes $a^{*}$. Our solution of the control problem consists of three steps:

- Formulation as maximization-problem: Compute a maximum $X \in 2^{N}$ such that $a^{*}$ wins in the restricted election $\left(X, A,\left(A_{i}\right)_{i \in X}\right)$. Then all alternatives from $N \backslash X$ are to remove.
- Relation-algebraic specification of the vector of candidetes sets

$$
\text { cand : } 2^{N} \leftrightarrow \mathbf{1}
$$

such that cand ${ }_{X}$ iff $a^{*}$ wins in $\left(X, A,\left(A_{i}\right)_{i \in X}\right)$.

- Relation-algebraic specification of the vector of solutions

$$
\text { sol }=\text { cand } \cap \overline{\overline{\mathrm{S}}^{\top} ; \text { cand }: 2^{N} \leftrightarrow \mathbf{1}}
$$

that describes the maximum sets in the set of sets described by cand.

## Specification of the Vector of Candidates Sets

Let an arbitrary set $X \in 2^{N}$ be given. Since

$$
(P ; p)_{i} \Longleftrightarrow \exists a \in A: P_{i, a} \wedge p_{a} \Longleftrightarrow \exists a \in A: P_{i, a} \wedge a=a^{*} \Longleftrightarrow P_{i, a^{*}}
$$ for all $i \in N$, we get for all $Y \in 2^{N}$ that

$$
\begin{array}{rlr} 
& \left\{i \in X \mid a^{*} \in A_{i}\right\}=Y & \\
\Longleftrightarrow & \left\{i \in X \mid P_{i, a^{*}}\right\}=Y & P \text { model } \\
\Longleftrightarrow & \forall i \in N:\left(i \in X \wedge P_{i, a^{*}}\right) \leftrightarrow i \in Y & \\
\Longleftrightarrow & \forall i \in N:\left(i \in X \wedge(P ; p)_{i}\right) \leftrightarrow i \in Y & \text { see above } \\
\Longleftrightarrow & \forall i \in N:\left(\mathrm{M}_{i, X} \wedge(P ; p ; \mathrm{L})_{i, X} \leftrightarrow \mathrm{M}_{i, Y}\right. & \text { definition M } \\
\Longleftrightarrow & \forall i \in N:(\mathrm{M} \cap P ; p ; \mathrm{L})_{i, X} \leftrightarrow \mathrm{M}_{i, Y} & \\
\Longleftrightarrow & \underbrace{\operatorname{syq}(\mathrm{M} \cap P ; p ; \mathrm{L}, \mathrm{M})}_{E} X, Y & \text { property syq }
\end{array}
$$

$\ldots$ and for all $Z \in 2^{N}$ and $b \in A$ that

$$
\begin{array}{rlr} 
& Z=\left\{i \in X \mid b \in A_{i}\right\} & \\
\Longleftrightarrow & Z=\left\{i \in X \mid P_{i, b}\right\} & P \text { model } \\
\Longleftrightarrow & \forall i \in N: i \in Z \leftrightarrow\left(i \in X \wedge P_{i, b}\right) & \\
\Longleftrightarrow & \forall i \in N: \mathrm{M}_{i, Z} \leftrightarrow\left(\mathrm{M}_{i, X} \wedge P_{i, b}\right) & \text { definition M } \\
\Longleftrightarrow & \forall i \in N: \mathrm{M}_{i, Z} \leftrightarrow\left[\mathrm{M}, P \rrbracket_{i,(X, b)}\right. & \text { property tupling } \\
\Longleftrightarrow & \underbrace{\operatorname{syq}(\mathrm{M},[\mathrm{M}, P \rrbracket)}_{F} Z,(X, b) & \text { property syq }
\end{array}
$$

yielding the relations

$$
E=\operatorname{syq}(\mathrm{M} \cap P ; p ; \mathrm{L}, \mathrm{M}): 2^{N} \leftrightarrow 2^{N}
$$

where $L: \mathbf{1} \leftrightarrow 2^{N}$, and

$$
F=\operatorname{syq}\left(\mathrm{M},[\mathrm{M}, P \rrbracket): 2^{N} \leftrightarrow 2^{N} \times A\right.
$$

... and

$$
\begin{aligned}
& a^{*} \text { wins in }\left(X, A,\left(A_{i}\right)_{i \in X}\right) \\
\Longleftrightarrow & \forall b \in A:\left|\left\{i \in X \mid a^{*} \in A_{i}\right\}\right| \geq\left|\left\{i \in X \mid b \in A_{i}\right\}\right| \\
\Longleftrightarrow & \neg \exists b \in A:\left|\left\{i \in X \mid a^{*} \in A_{i}\right\}\right|<\left|\left\{i \in X \mid b \in A_{i}\right\}\right| \\
\Longleftrightarrow & \neg \exists b \in A:\left(E ; \overline{\mathrm{S}}^{\top} ; F\right)_{X,(X, b)} \\
\Longleftrightarrow & \neg \exists U \in 2^{N}, b \in A:\left(E ; \bar{S}^{\top} ; F\right)_{X,(U, b)} \wedge U=X \\
\Longleftrightarrow & \neg \exists U \in 2^{N}, b \in A:\left(E ; \overline{\mathrm{S}}^{\top} ; F\right)_{X,(U, b)} \wedge \pi_{(U, b), X} \\
\Longleftrightarrow & \neg \exists U \in 2^{N}, b \in A:\left(E ; \overline{\mathrm{S}}^{\top} ; F \cap \pi^{\top}\right)_{X,(U, b)} \wedge \mathrm{L}_{(U, b)} \\
\Longleftrightarrow & \underbrace{\left(E ; \overline{\mathrm{S}}^{\top} ; F \cap \pi^{\top}\right) ; \mathrm{L}}_{\text {cand }} x
\end{aligned}
$$

yielding the vector

$$
\text { cand }=\overline{\left(E ; \cap \overline{\mathrm{S}}^{\top} ; F \cap \pi^{\top}\right) ; \mathrm{L}}: 2^{N} \leftrightarrow \mathbf{1},
$$

where $\mathrm{L}: 2^{N} \times A \leftrightarrow \mathbf{1}$.

## Concluding Remarks

Present and future work:

- Investigation of further voting systems.
- Condorcet voting (AAMAS 2014, May 2014).
- Plurality voting (CASC 2014, submitted).
- ...
- Investigation of further types of manipulation.
- Control by partition.
- Bribery.
- Investigation of further methods of solutions.
- Functional programming.
- Constraint programming.
- Binary integer programming.
- Bio-inspired techniques.
- Heuristics
- ...

