

# Algebras in type-2 fuzzy sets

John Harding, Carol and Elbert Walker

New Mexico State University  
[www.math.nmsu.edu/~JohnHarding.html](http://www.math.nmsu.edu/~JohnHarding.html)  
[jharding@nmsu.edu](mailto:jharding@nmsu.edu)

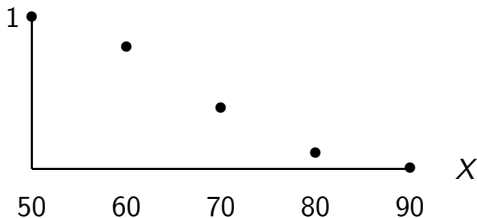
Denver, October 2016

## Type-1 fuzzy sets

$$X = \{50, 60, 70, 80, 90\}$$

A type-1 fuzzy subset of  $X$  is a map  $\text{COLD} : X \rightarrow [0, 1]$

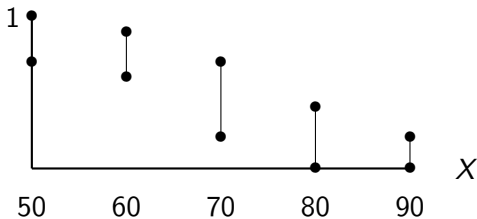
The expert's belief that 60 is cold is 0.8.



## Interval valued fuzzy sets

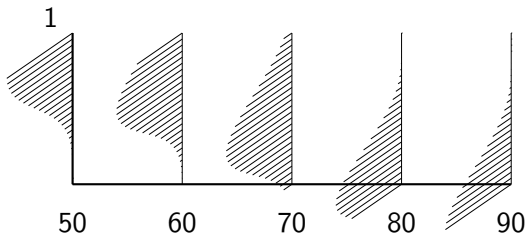
This is a map  $\text{COLD} : X \rightarrow \{(a, b) \in [0, 1]^2 : a \leq b\}$ .

The expert's belief that 60 is cold is between  $[0.6, 0.9]$ .



## Type-2 fuzzy sets

A type-2 fuzzy subset is  $\text{COLD} : X \rightarrow \{f \mid f : [0, 1] \rightarrow [0, 1]\}$



## Truth value algebras

The truth value algebras for fuzzy sets, interval valued fuzzy sets, and type-2 fuzzy sets are

$$I = [0, 1]$$

$$I^{[2]} = \{(a, b) : a \leq b \in I\}$$

$$M = \{f \mid f : I \rightarrow I\}$$

$I$  and  $I^{[2]}$  sit in  $M$  as characteristic functions of points and intervals

## Operations

$I$  and  $I^{[2]}$  are De Morgan algebras. One also considers t-norms and conorms on these.

**Definition (Zadeh)** Define the following operations on  $M$

1.  $(f \sqcap g)(x) = \bigvee \{(f(y) \wedge g(z)) : y \wedge z = x\}$
2.  $(f \sqcup g)(x) = \bigvee \{(f(y) \wedge g(z)) : y \vee z = x\}$
3.  $f^*(x) = f(1 - x)$
4.  $0(x) = 1$  if  $x = 0$  and  $0$  otherwise
5.  $1(x) = 1$  if  $x = 1$  and  $0$  otherwise

These are **convolutions** of the corresponding operations on  $I$ . We can also convolute t-norms  $\Delta$  and conorms on  $I$ .

## Equations

**Theorem**  $M$  satisfies the equations for De Morgan algebras except that absorption and distributivity are weakened to the following.

1.  $x \cap (x \cup y) = x \cup (x \cap y)$
2.  $(x \cap y) \cup (x \cap z) \cup (y \cap z) = (x \cup y) \cap (x \cup z) \cap (y \cup z)$

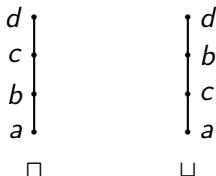
$M$  is not a lattice.

The unbalanced distributive laws do not hold.

$M$  is a type of thing known as a De Morgan Birkhoff system.

## Equations

**Theorem** The variety  $V(M)$  is generated by a finite algebra. The variety generated by the reduct  $(M, \sqcap, \sqcup)$  is generated by



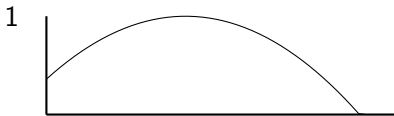
**Proof**  $V(M)$  is generated by the complex algebra of any bounded chain with involution that has at least 5 elements.

So these varieties have solvable free word problems. We do not know if they are finitely based.



## A related algebra

**Definition** A function  $f : I \rightarrow I$  is convex normal if it goes up to 1, then down.



Convex normal functions are a not too restrictive setting for our desired use as belief functions.

## A related algebra

**Theorem** The convex normal functions are a subalgebra of  $M$ . For the quotient  $L$  of this subalgebra modulo agreement c.a.e.

1.  $L$  is a complete, completely distributive DeMorgan algebra
2.  $L$  is a compact Hausdorff topological algebra
3.  $\int_0^1 |f(x) - g(x)| dx$  is a metric on it

Further, the convolution  $\Delta$  of any continuous t-norm on  $I$  gives a commutative quantale structure  $(L, \Delta, \vee)$ .

## A purpose

**Aim:** extend the theory of fuzzy controllers to the type-2 setting.

### An example

We have a room with a device in it to heat and cool the room and a sensor that measures approximate temperature. Our controller is to adjust the setting of the device.

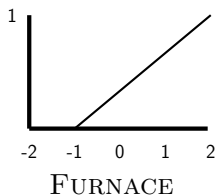
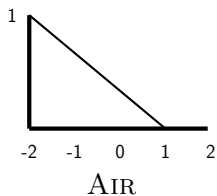
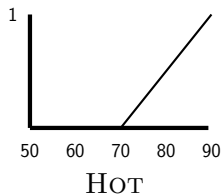
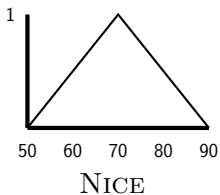
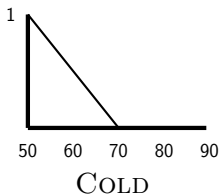
$X = \{50, 60, 70, 80, 90\}$  possible temperatures

$Y = \{-2, -1, 0, +1, +2\}$  settings of the device

A setting of -2 puts lots of cold air in the room, +2 lots of hot air.

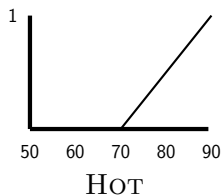
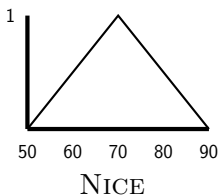
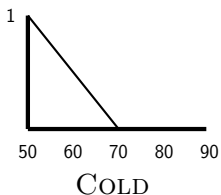
## Type-1 fuzzy controllers

Make linguistic variables COLD, NICE, and HOT for temperature; AIR and FURNACE for settings. Experts give fuzzy sets for these.



## Type-1 fuzzy controllers

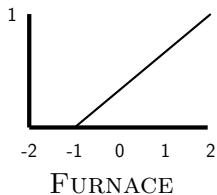
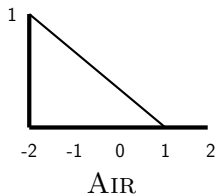
We represent the fuzzy sets for temperature as a matrix


$$P = \begin{pmatrix} 1 & .5 & 0 & 0 & 0 \\ 0 & .5 & 1 & .5 & 0 \\ 0 & 0 & 0 & .5 & 1 \end{pmatrix}$$

	50	60	70	80	90
COLD	1	.5	0	0	0
NICE	0	.5	1	.5	0
HOT	0	0	0	.5	1

## Type-1 fuzzy controllers

And do the same for adjustments



$$Q = \begin{pmatrix} 1 & .7 & .3 & 0 & 0 \\ 0 & 0 & .3 & .7 & 1 \end{pmatrix}$$

	-2	-1	0	1	2
AIR	1	.7	.3	0	0
FURNACE	0	0	.3	.7	1

## Type-1 fuzzy controllers

We are given a rule base that says what should be done in each case.

$$R = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

	COLD	NICE	HOT
AIR	0	1	1
FURNACE	1	0	0

## Type-1 fuzzy controllers

Then if our sensor gives a reading of 80 for temperature we make a column vector  $\hat{T}$  with a 1 in the spot for 80 and 0's elsewhere and compute  $Q^T R P(\hat{T})$

$$\begin{pmatrix} 1 & 0 \\ .7 & 0 \\ .3 & .3 \\ 0 & .7 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & .5 & 0 & 0 & 0 \\ 0 & .5 & 1 & .5 & 0 \\ 0 & 0 & 0 & .5 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} .5 \\ .3 \\ .2 \\ 0 \\ 0 \end{pmatrix}$$

The result is a fuzzy subset of  $Y = \{-2, -1, 0, 1, 2\}$  that we then “defuzzify” to get an adjustment to the device.



## Type-1 fuzzy controllers

Matrix multiplication computes entries as sums of products.

This multiplication was done using  $\cdot$  as product and  $\vee$  as sum. It can be done using any continuous t-norm  $\Delta$  as product and  $\vee$  as sum. This requires

$$x \Delta \bigvee y_i = \bigvee (x \Delta y_i)$$

to obtain associativity of matrix multiplication.

## Symmetric monoidal categories

Ordinary fuzzy controllers live in the symmetric monoidal category of matrices over  $(I, \Delta, \vee)$ .

Objects: sets

Morphisms: matrices composed by multiplication

Tensor product is ordinary product of sets and Kronecker products of matrices. It allows to have more dependent or independent variables in the controller.

## Type-2 fuzzy controllers

Do exactly the same with the category of matrices over  $(L, \Delta, \vee)$ .

# Practicality

Implementations would require some restriction on the functions  $f : I \rightarrow I$  (taking  $n$  values, or with  $n$  linear peices)

Algorithms for  $\sqcap$ ,  $\sqcup$  of convex normal functions are linear in  $n$ .

Thanks for listening.

Papers at [www.math.nmsu.edu/~jharding](http://www.math.nmsu.edu/~jharding)